

A new estimator for the tail-dependence coefficient

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Abstract: Recently, the concept of tail dependence has been discussed in financial applications related to market or credit risk. The multivariate extreme value theory is a proper tool to measure and model dependence, for example, of large loss events. A common measure of tail dependence is given by the so-called tail-dependence coefficient. We present a simple estimator of this latter that avoids the drawbacks of the estimation procedure that has been used so far. We prove strong consistency and asymptotic normality and analyze the finite sample behavior through simulation. We illustrate with an application to financial data.

Keywords: extreme value theory, tail-dependence coefficient, stable tail dependence function

1 Introduction

Modern risk management is highly interested in assessing the amount of extremal dependence, a growing phenomena in recent time periods of volatile and bear markets. Correlation itself is not enough to describe a tail dependence structure and often results in misleading interpretations (see e.g. Embrechts *et al.* [3], 2002 for examples).

Multivariate Extreme value theory (EVT) is the natural tool to deal with tail dependence. The so-called *tail-dependence coefficient* (TDC) has become a popular measure in risk management. It is usually denoted λ and measures the probability of occurring extreme values for one random variable (r.v.) given that another assumes an extreme value too. More precisely,

$$\lambda = \lim_{t \downarrow 0} P(F_X(X) > 1 - t | F_Y(Y) > 1 - t), \quad (1)$$

where F_X and F_Y are the distribution functions (d.f.'s) of r.v.'s X and Y , respectively. The TDC characterizes the dependence in the tail of a random pair (X, Y) , in the sense that, $\lambda > 0$ corresponds to tail dependence whose degree is measured by the value of λ , and $\lambda = 0$ means tail independence. Due to the emergent importance of this issue, it is not surprising that the implementation of tail dependence measures and respective estimation have attracted the attention of investigators. Sibuya ([17], 1960), Tiago de Oliveira ([18], 1962-63), Ledford and Tawn ([13, 14], 1996, 1997), Joe ([10], 1997), Coles *et al.* ([2], 1999), Embrechts *et al.* ([4], 2003), Frahm *et al.* ([8], 2005), Schmidt and Stadtmüller ([16], 2006), Ferreira and Ferreira ([6], 2011), are some references on this topic. Curiously, the first tail dependence concept appearing in literature concerns the TDC, as far back in the sixties with Sibuya ([17], 1960). More precisely, for Normal distributed random pairs, Sibuya ([17], 1960) shows that no matter how high we choose the correlation, if we go far enough into the tail, extreme events appear to occur independently in each margin.

Here we shall present an estimator for the TDC based on a new procedure that avoids the main drawback of existing ones. Strong consistency and asymptotic normality are stated and the finite sample behavior is illustrated through simulation. An application to financial data is presented at the end.

2 EVT and tail dependence

The main objective of an extreme value analysis is to estimate the probability of events that are more extreme than any that have already been observed. The tools within EVT, in particular the use of extremal models, enables extrapolations of this type. The central result in univariate Extreme Value Theory (EVT) states that, for an i.i.d. sequence, $\{X_n\}_{n \geq 1}$, having common distribution function (d.f.) F , if there are real constants $a_n > 0$ and b_n such that,

$$P(\max(X_1, \dots, X_n) \leq a_n x + b_n) = F^n(a_n x + b_n) \xrightarrow{n \rightarrow \infty} G(x), \quad (2)$$

for some non degenerate function G_γ , then it must be a Generalized Extreme Value function (GEV),

$$G(x) = \exp(-(1 + \gamma x)^{-1/\gamma}), \quad 1 + \gamma x > 0, \quad \gamma \in \mathbb{R},$$

(for $\gamma = 0$, $G(x) = \exp(-e^{-x})$) and we say that F belongs to the max-domain of attraction of G , in short, $F \in \mathcal{D}(G)$. The parameter γ , known as the tail index, is a shape parameter as it determines the tail behavior of F , being so a crucial issue in EVT. More precisely, if $\gamma > 0$ we are in the domain of attraction Fréchet corresponding to a heavy tail, $\gamma < 0$ indicates the Weibull domain of attraction of light tails and $\gamma = 0$ means a Gumbel domain of attraction and an exponential tail.

Models for dependent or non-identical distributed r.v.'s have also been developed (see, for instance, Leadbetter [12] 1983 and Meijzler [15] 1956, respectively).

In a multivariate framework, an extension of the univariate limiting result in (2) is considered and the multivariate maximum corresponds to the vector of component-wise maxima. Let $\{\mathbf{X}_n = (X_{n,1}, \dots, X_{n,d})\}_{n \geq 1}$ be an i.i.d. sequence of d -dimensional random vectors with common d.f. F . If there are real vectors of constants \mathbf{b}_n and positive \mathbf{a}_n such that,

$$P(\max(\mathbf{X}_1, \dots, \mathbf{X}_n) \leq \mathbf{a}_n \mathbf{x} + \mathbf{b}_n) = F^n(\mathbf{a}_n \mathbf{x} + \mathbf{b}_n) \xrightarrow{n \rightarrow \infty} G(\mathbf{x}), \quad (3)$$

for some non degenerate function G , then it must be a multivariate extreme value distribution (MEV), given by

$$G(\mathbf{x}) = \exp(-l(-\log G_1(x_1), \dots, -\log G_d(x_d))),$$

for some d -variate function l , where G_j , $j = 1, \dots, d$, is the marginal d.f. of G . We also say that F belongs to the max-domain of attraction of G , in short, $F \in \mathcal{D}(G)$. The function l in (4) is called *stable tail dependence function*.

Let F_j be the marginal d.f. of F . Since a sequence of random vectors can only converge in distribution if the corresponding marginal sequences do, we have, for $j = 1, \dots, d$,

$$F_j^n(a_{n,j}x_j + b_{n,j}) \xrightarrow{n \rightarrow \infty} G_j(x_j)$$

Hence G_j is a GEV and F_j is in its domain of attraction.

In order to study the dependence structure of a MEV, it is convenient to standardize the margins so that they are all the same. A particular useful choice is the unit Fréchet, $\exp(-1/x)$ (observe that unit Fréchet marginals can be obtained by transformation $-1/\log F_j(X_j)$ for $j \in I \subset \{1, \dots, d\}$), and the stable tail dependence function l in (4) becomes

$$l(\mathbf{v}) = -\log G(v_1^{-1}, \dots, v_d^{-1}), \mathbf{v} \in [\mathbf{0}, \infty). \quad (4)$$

Thus l satisfies an important homogeneity property (of order 1) and hence, it is easy to establish that, except for the special case of independence, all bivariate extreme value distributions (BEV) are tail dependent ($\lambda > 0$). Furthermore, we have

$$\lambda = 2 - l(1, 1). \quad (5)$$

Examples of parametric BEV models

- *Logistic*: $l(v_1, v_2) = (v_1^1/r + v_2^1/r)^r$, with $v_j \geq 0$ and parameter $0 < r \leq 1$; complete dependence is obtained in the limit as $r \rightarrow 0$ and independence when $r = 1$.
- *Asymmetric Logistic*: $l(v_1, v_2) = (1 - t_1)v_1 + (1 - t_2)v_2 + ((t_1v_1)^1/r + (t_2v_2)^1/r)^r$, with $v_j \geq 0$ and parameters $0 < r \leq 1$ and $0 \leq t_j \leq 1$, $j=1,2$; when $t_1 = t_2 = 1$ the asymmetric logistic model is equivalent to the logistic model; independence is obtained when either $r = 1$, $t_1 = 0$ or $t_2 = 0$. Complete dependence is obtained in the limit when $t_1 = t_2 = 1$ and r approaches zero.
- *Hüsler-Reiss*: $l(v_1, v_2) = v_1\Phi(r^{-1} + \frac{1}{2}r \log(v_1/v_2)) + v_2\Phi(r^{-1} + \frac{1}{2}r \log(v_2/v_1))$, with parameter $r > 0$ and where Φ is the standard normal d.f.; complete dependence is obtained as $r \rightarrow \infty$ and independence as $r \rightarrow 0$.

3 Estimation

The d -variate stable tail dependence function in (4) can also be formulated as

$$\lim_{t \rightarrow \infty} tP\left(F_1(X_1) > 1 - \frac{x_1}{t} \vee \dots \vee F_d(X_d) > 1 - \frac{x_d}{t}\right) \quad (6)$$

since, by applying the unit Fréchet marginals, we have successively,

$$\begin{aligned} & \lim_{t \rightarrow \infty} tP\left(F_1(X_1) > 1 - \frac{x_1}{t} \vee \dots \vee F_d(X_d) > 1 - \frac{x_d}{t}\right) \\ &= \lim_{t \rightarrow \infty} tP\left(X_1 > \frac{t}{x_1} \vee \dots \vee X_d > \frac{t}{x_d}\right) \\ &= \lim_{t \rightarrow \infty} tP\left(X_1 > \frac{t}{x_1} \vee \dots \vee X_d > \frac{t}{x_d}\right) \\ &= \lim_{t \rightarrow \infty} t\left(1 - F\left(\frac{t}{x_1}, \dots, \frac{t}{x_d}\right)\right) \\ &= \lim_{t \rightarrow \infty} -\log F^t\left(\frac{t}{x_1}, \dots, \frac{t}{x_d}\right) \\ &= -\log G\left(\frac{1}{x_1}, \dots, \frac{1}{x_d}\right). \end{aligned} \quad (7)$$

Therefore, based on (5) and (7), the TDC in (1) can be stated like follows:

$$\lambda = 2 - \lim_{t \rightarrow \infty} tP\left(F_1(X_1) > 1 - \frac{1}{t} \vee F_2(X_2) > 1 - \frac{1}{t}\right). \quad (8)$$

Huang (1992 [9]), considered the estimator based on (8) by plugging-in the respective empirical counterparts,

$$\widehat{\lambda}^{(H)} = 2 - \frac{1}{k_n} \sum_{i=1}^n \mathbf{1}_{\{\widehat{F}_1(X_1) > 1 - \frac{k_n}{n} \vee \widehat{F}_2(X_2) > 1 - \frac{k_n}{n}\}}, \quad (9)$$

where \widehat{F}_j is the empirical d.f. of F_j , $j = 1, 2$. Concerning estimation accuracy, some modifications of this latter may be used, like replacing the denominator n by $n + 1$, i.e., considering

$$\widehat{F}_j(u) = \frac{1}{n+1} \sum_{k=1}^n \mathbf{1}_{\{X_j^{(k)} \leq u\}}$$

(for a discussion on this topic see, for instance, Beirlant et al. [1] 2004). The consistency and asymptotic normality of estimator $\widehat{\lambda}^{(H)}$ is derived under the condition that $\{k_n\}$ is an intermediate sequence, i.e., $k_n \rightarrow \infty$ and $k_n/n \rightarrow 0$, as $n \rightarrow \infty$. The choice of the value k in the sequence $\{k_n\}$ that allows the better trade-off between bias and variance is of major difficulty, since small values of k come along with a large variance whenever an increasing k results in a strong bias. Therefore, simulation studies have been carried out in order to find the best value of k that allows this compromise. The other estimators, either for the stable tail dependence function l or for the TDC, that have been considered in literature (for a survey, see for instance, respectively, Krajina [11] 2010 and Frahm *et al.* [8] 2005) are also based on asymptotic results with the same drawback of including an intermediate sequence, already referred above.

The approach that is presented here avoid this problem. It is based on an estimation procedure for the stable tail dependence function only involving a sample mean. More precisely, by Proposition 3.1 in Ferreira and Ferreira ([7], 2011), we have that

$$l(x_1, x_2) = \frac{E(F_1(X_1)^{1/x_1} \vee F_2(X_2))^{1/x_2}}{1 - E(F_1(X_1)^{1/x_1} \vee F_2(X_2))^{1/x_2}}. \quad (10)$$

Therefore, based on (5) and (10) we propose estimator

$$\widehat{\lambda} = 3 - (1 - \overline{\widehat{F}_1(X_1) \vee \widehat{F}_2(X_2)})^{-1} \quad (11)$$

where $\overline{\widehat{F}_1(X_1) \vee \widehat{F}_2(X_2)}$ is the sample mean of $\widehat{F}_1(X_1) \vee \widehat{F}_2(X_2)$, i.e.,

$$\overline{\widehat{F}_1(X_1) \vee \widehat{F}_2(X_2)} = \frac{1}{n} \sum_{i=1}^n [\widehat{F}_1(X_1^{(i)}) \vee \widehat{F}_2(X_2^{(i)})].$$

Proposition 3.1. *Estimator $\widehat{\lambda}$ in (11) is asymptotically normal whenever F has continuous marginals and continuous partial derivatives. Moreover it is strong consistent.*

Dem. By Fermanian *et al.* ([5], 2002, Theorem 6), we have that

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n \{J(\widehat{F}_1(X_1^{(i)}), \widehat{F}_2(X_2^{(i)})) - E(J(\widehat{F}_1(X_1^{(i)}), \widehat{F}_2(X_2^{(i)})))\} \rightarrow \int_{[0,1]^d} \mathbb{G}(u_1, u_2) dJ(u_1, u_2)$$

in distribution in $\ell^\infty([0, 1]^2)$, where the limiting process and \mathbb{G} are centered Gaussian, and $J(u_1, u_2) = \max(u_1, u_2)$, $(u_1, u_2) \in [0, 1]^2$. The asymptotic normality is now derived from

a general version of the Delta Method as considered in Schmidt and Stadtmüller [16] (2006; Theorem 13).

The strong consistency is straightforward from Proposition 3.7 in Ferreira and Ferreira ([7], 2011). \square

Remark 3.1. *Observe that, if the marginals F_j , $j = 1, 2$, in (11) are known, the asymptotic normality of $\hat{\lambda}$ is straightforward by the Central Limit Theorem and the usual Delta Method. More precisely,*

$$\sqrt{n}(\hat{\lambda} - \lambda) \rightarrow N(0, \sigma^2), \quad (12)$$

where

$$\sigma^2 = \frac{l(1,1)(1+l(1,1))^2}{(2+l(1,1))}.$$

Details of the calculations can be seen in Proposition 3.3 of Ferreira and Ferreira ([7], 2011). The strong consistency is also immediately derived from the sample mean.

3.1 Simulations

We consider 1000 independent copies of $n = 50, 100, 500, 1000$ i.i.d. pseudo-random vectors generated from three different BEV models considered in Section 2: logistic, asymmetric logistic and Hüsler-Reiss. We estimate the TDC through our estimator ($\hat{\lambda}$). For comparison, we also compute estimator $\hat{\lambda}^{(H)}$ and, the required choice of k to balance the variance-bias problem is based on the procedure in Schmidt and Stadtmüller ([16], 2006). The empirical bias and the root mean-squared error (rmse) for all implemented TDC estimations are derived and presented in Table 1. Our estimator $\hat{\lambda}$ clearly outperforms estimator $\hat{\lambda}^{(H)}$.

3.2 Application to financial data

We shall see evidence of tail dependence in financial data. We consider the monthly maximum of the negative log-returns of Dow Jones and NASDAQ index for the time period 1994-2004. The corresponding scatter plot and TDC estimate plot of $\hat{\lambda}^{(H)}$ for various k (Figure 1) show the presence of tail dependence and the order of magnitude of the tail-dependence coefficient. Moreover, the typical variance-bias problem for various threshold values k can be observed, too. In particular, a small k induces a large variance, whereas an increasing k generates a strong bias of the TDC estimate. The threshold choosing procedure of k used in Section 3 leads to a TDC estimate of $\hat{\lambda}^{(H)} = 0.5556$ and from our estimator we derive $\hat{\lambda} = 0.5268$.

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Table 1: Sample absolute bias and RMSE of the non-parametric TDC estimators $\hat{\lambda}$ and $\hat{\lambda}^{(H)}$ for BEV Logistic, Asymmetric Logistic and Hüsler-Reiss models.

Logistic ($r = 0.7$)		
$\lambda = 0.3755$	$\hat{\lambda}$	$\hat{\lambda}^{(H)}$
	bias (rmse)	bias (rmse)
(n=50)	0.0019 (0.0994)	0.0395 (0.1962)
(n=100)	0.0052 (0.0711)	0.0389 (0.1412)
(n=500)	0.0006 (0.0330)	0.0216 (0.0883)
(n=1000)	0.0002 (0.0232)	0.0099 (0.1379)

Asym. Logistic ($r = 0.7, t_1 = t_2 = 0.5$)		
$\lambda = 0.1877$	$\hat{\lambda}$	$\hat{\lambda}^{(H)}$
	bias (rmse)	bias (rmse)
(n=50)	0.0085 (0.1147)	0.0527 (0.1836)
(n=100)	0.0053 (0.0824)	0.0635 (0.1363)
(n=500)	0.0020 (0.0389)	0.0335 (0.0847)
(n=1000)	0.0014 (0.0287)	0.0038 (0.1193)

Hüsler-Reiss($r = 0.7$)		
$\lambda = 0.1531$	$\hat{\lambda}$	$\hat{\lambda}^{(H)}$
	bias (rmse)	bias (rmse)
(n=50)	0.0119 (0.1293)	0.0729 (0.1893)
(n=100)	0.0077 (0.0838)	0.0706 (0.1387)
(n=500)	0.0020 (0.0383)	0.0378 (0.0851)
(n=1000)	0.0020 (0.0293)	0.0060 (0.1084)

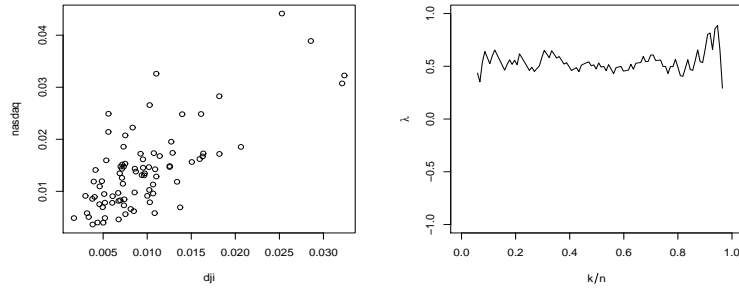


Figure 1: Scatter plot of Dow Jones versus NASDAQ monthly maximum negative log-returns ($n = 84$ data points) and the corresponding TDC estimates $\hat{\lambda}^{(H)}$ for various k/n .

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